

# High-field cantilever magnetometry as a tool for the determination of the magnetocrystalline anisotropy of single crystals

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## Abstract

Cantilever torque magnetometry is utilized widely in physics and material science for the determination of magnetic properties of thin films and semiconductors. Here, we report on its first application in rock magnetism, namely the determination of  $K_1$  and  $K_2$  of single crystal octahedra of natural magnetite. The design of cantilever magnetometers allows optimization for the specific research question at hand. For the present study, a cantilever magnetometer was used that enables measurement of samples with a volume up to 64 mm<sup>3</sup>. It can be inserted into an electromagnet with a maximum field of 2 T. The cantilever spring is suitable for torque values ranging from  $7.5 \times 10^{-7}$  N·m to  $5 \times 10^{-6}$  N·m. The torque is detected capacitively; the measured capacitance is converted into torque by using a calibrated feedback coil. The magnetometer allows in-situ rotation of the sample in both directions and is, therefore, also suitable to analyze rotational hysteresis effects.

The evaluation of the magnetite anisotropy constants involved Fourier analysis of the torque signal on the magnetite crystals' (001) and (110) planes. The absolute anisotropy constant has been computed using the extrapolation-to-infinite-field method. The value of  $K_1$  at room temperature is determined at  $-1.28 \times 10^4$  [J m<sup>-3</sup>] ( $\pm 0.13$ , i.e. 10%) and that of  $K_2$  at  $-2.8 \times 10^3$  [J m<sup>-3</sup>] ( $\pm 0.1$ , i.e. 2%). These values concur with earlier determinations that could not provide an instrumental error, in contrast with this work.

The cantilever magnetometer performs four times faster than other torque magnetometers used for rock magnetic studies. This makes the instrument also suitable for magnetic fabric analysis.

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## 1. Introduction

Magnetite is the most abundant magnetic mineral in terrestrial rocks and its magnetic properties have therefore been studied intensively (summarized in O'Reilly, 1984; Dunlop and Özdemir, 1997). It is a cubic mineral crystallizing in the spinel structure, with anisotropy constants at room temperature  $K_1 = -1.35 \times 10^4$  [J m<sup>-3</sup>] and  $K_2 = -2.80 \times 10^3$  [J m<sup>-3</sup>] (Syono, 1965). Despite the

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importance of knowing these values as exact as possible for micromagnetic calculations (e.g., Enkin and Dunlop, 1987; Williams and Dunlop, 1989; Williams and Wright, 1998) or for theoretical models of first-order-reversal-curves (FORC) diagrams (Carvallo et al., 2003),  $K_1$  has been evaluated only on a few occasions (Syono, 1965; Sawaoka and Kawai, 1967; Fletcher and O'Reilly, 1974; Kakol et al., 1991), while  $K_2$  has been determined only twice (Bickford et al., 1957; Syono, 1965).

The most common technique to determine magnetic anisotropy constants is the torque magnetometer (Tarasov and Bitter, 1937; Burd et al., 1977; Huq and Lee, 1978). While AC bridge-type susceptometers are very precise for the determination of the anisotropy ellipsoids of the low-field or initial susceptibility, torque magnetometers can measure the anisotropy in much higher magnetic fields as well (up to a few Tesla). For rock samples, the anisotropy of the high field magnetic susceptibility in terms of directions and shape of the ellipsoid was calculated on basis of torque magnetometer data (Banerjee and Stacey, 1967; Parma, 1988; Bergmüller et al., 1994). Often the total fabric is composed of several subfabrics and Hrouda and Jelinek (1990) and Martín-Hernández and Hirt (2004) were able to compute the separate anisotropy tensors of paramagnetic and ferrimagnetic minerals by means of torque measurements in several fields. When ferrimagnetic minerals are measured in applied magnetic fields above saturation, the magnetic torque is constant with applied field, while for paramagnetic minerals the torque is proportional to the square of the field. These different field dependencies are used to separate the two anisotropy tensors. However, the torque magnetometers up to now are designed for standard paleomagnetic specimens (25.4 mm diameter and 22 mm height); they are less suited for a proper measurement on much smaller single crystals, being either synthetic or of natural origin.

Recently, sensitive microcantilever torque magnetometers have been developed to accurately evaluate the magnetic anisotropy in thin films and recording media (Löhndorf et al., 2000; Hopfl et al., 2001). They allow also the determination of rotational hysteresis, to estimate the degree of magnetic exchange interaction, being very effective in ferrimagnetic and antiferromagnetic phases (Yoshida et al., 1994; Koike et al., 1999; Vopsaroiu and Bissell, 2002). Here, we report on a cantilever magnetometer that operates in fields from 0 to 2 T and that can measure specimens with sizes up to  $4 \times 4 \times 4 \text{ mm}^3$ , ideal for the determination of the anisotropy constants of natural ferromagnetic single crystals. Instrumental characteristics, drift and how to

cope with it, limits of detection, performance in terms of measurement duration are described for five natural single crystals of magnetite. We confirm earlier measurements of  $K_1$  and  $K_2$  with experimental error never evaluated before. The potential for rock samples is discussed and full anisotropy evaluation of other natural magnetic minerals is envisaged in the future.

## 2. High-field cantilever magnetometer

In material sciences, cantilever torque magnetometers are relatively well known, most are so-called microcantilevers based on capacitive torque detection (Chaparala et al., 1992; Rossel et al., 1998). Such a cantilever is based on a capacitor with a certain inter-plate distance  $d$  (Fig. 1). The two plates are connected by a flexible membrane that allows variation of the distance between the two plates. This flexible tongue is connected to a fixed platform through a beam (Fig. 1b). The instrument has a feedback coil on top of the upper capacitor plate for calibration purposes. The coil is wound around a plastic cylinder on top of which the sample can be placed (Fig. 1b).

In the presence of a magnetic field, the magnetization of an anisotropic sample is not exactly parallel to the direction of the applied field, but it has an angle  $\theta$ . The torque ( $\mathbf{T}$ ) exerted by a magnetic moment in the presence of a magnetic field is given by:

$$\mathbf{T} = \mathbf{m} \times \mathbf{B} \quad (1)$$

where  $\mathbf{m}$  is the magnetization and  $\mathbf{B}$  is the applied magnetic field. The direction of the torque is always perpendicular to the plane defined by  $\mathbf{m}$  and  $\mathbf{B}$ , and therefore it is a vector perpendicular to the frontal view shown in Fig. 1a. The effect of the torque is a change in the distance  $d$  between the two capacitor plates, which causes a variation in the capacitance.

A rotating wheel allows the cantilever to vary its orientation with respect to the direction of the applied field. A stepper motor is connected to the cantilever, which is operated by a personal computer. The capacitance, which is proportional to the torque, is evaluated as a function of angle. The whole cantilever set-up is placed between the poles of an electromagnet that can generate fields up to 2 T. The capacitance is read by an ultra-precision capacitance bridge model 2500A 1 kHz, manufactured by "Andeen Hagerling".

It is transformed into torque through the calibration coefficient determined with the feedback coil mounted on top of the upper capacitor plate (Fig. 1a), a method often used to calibrate torque magnetometers (Pearson, 1979). The current through the coil (3.5 mm in diameter

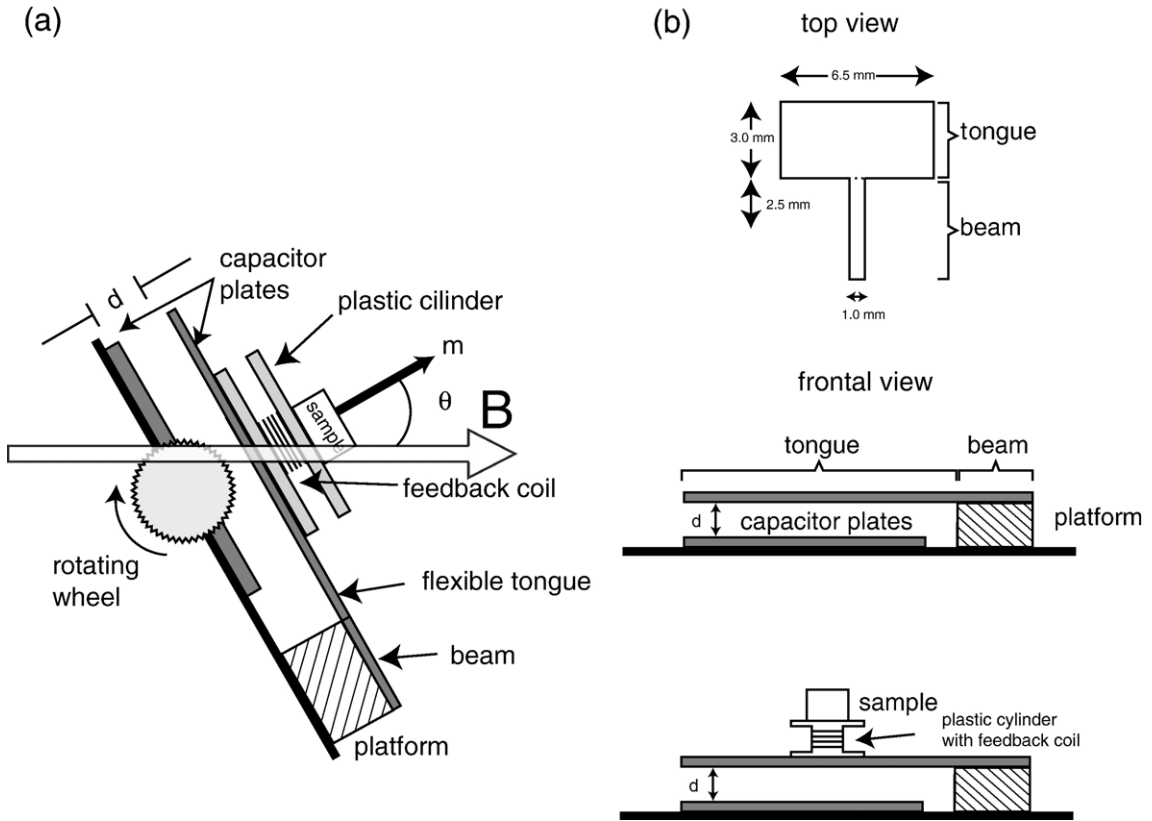


Fig. 1. Schematic drawing of the cantilever. (a) Lateral view of the cantilever showing the two plates that constitute the capacitor and their initial distance, the location of the calibrating feedback coil, flexible tongue and rotating wheel. (b) Detailed drawing of the location of the tongue and beam from top (above) and a lateral view (below). Lower most drawing shows the location of the sample on top of the feedback coil.

with 10 turns) can be changed; therefore it is possible to create a varying magnetization in the direction perpendicular to the coil plane. Its magnitude is  $m = nAi$  with  $m$  is the magnetization,  $n$  is the number of turns,  $A$  is the area of the coil and  $i$  is the electric current in A. The feedback is used for the calibration of the instrument. For several currents in the coil torque  $T$  is calculated and

with the corresponding measured capacitance the calibration constant is determined (Fig. 2a).

The feedback coil also allows the determination of the detection limit of the instrument. The coil is oriented  $90^\circ$  with respect to an applied field of 1.5 T. By changing the direction and amount of current through the feedback coil (steps of 10 mA, 5 mA, -5 mA and

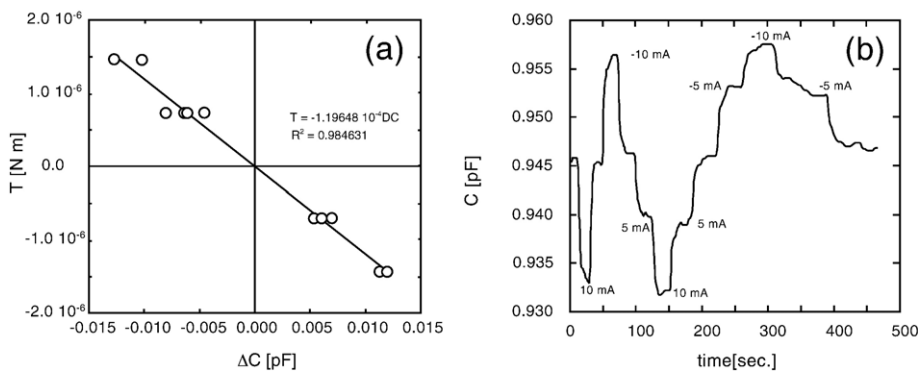


Fig. 2. (a) Capacitance measured while varying the applied current in a step-like manner. The magnetic field of 1.5 T is oriented perpendicular to the plane of the current coil. (b) Capacitance measured as a function of time for different currents through the feed-back coil.

–10 mA) it was established that 5 mA could be resolved (Fig. 2b). Using Eq. (1) the estimated minimum sensitivity is  $5 \times 10^{-7} \text{ Am}^2$ .

### 3. Description and rock magnetic properties of the samples

The analyzed samples are natural octahedral magnetite single crystals from a greenschist from Green Mill (Maryland, USA). Samples of approximately  $8 \text{ mm}^3$  have been selected because this is most suited for the cantilever. To determine the purity and domain state of the magnetite several rock magnetic experiments have been carried out.

The chemical composition is (values in g/kg) 680.5 Fe, 0.55 Al, 0.60 Ca, 0.05 K, 0.45 Mg, 0.85 Mn, 1.60 Ti (Franke et al., in preparation) corresponding to 0.67% non-Fe cations.

The Curie temperature was measured in air on a modified translation Curie balance (Mullender et al., 1993). The so-called incremental heating and cooling

segments protocol was used to detect chemical alteration; the final heating temperature was  $650^\circ\text{C}$ . The Curie temperature, determined by “intersecting tangent” method (Grommé et al., 1969; Moskowitz, 1981), is  $578 \pm 2^\circ\text{C}$  (Fig. 3a) indicative of pure magnetite (e.g., Dunlop and Özdemir, 1997). The 2nd derivative method (Tauxe, 1998) yielded the same estimate (within error margin) of  $577^\circ\text{C}$ .

Hysteresis loops were measured on an alternating gradient magnetometer (Princeton Inc. Micromag 2900 model) to determine the saturation magnetization ( $M_s$ ), remanent saturation ( $M_{rs}$ ), and coercive force ( $B_c$ ). As anticipated, the measurements show an almost closed loop, representative for the multidomain state. Saturation magnetization is about  $89 \text{ Am}^2/\text{kg}$  achieved in a field of about 250 mT, another indication of pure magnetite.

First-order reversal curve (FORC) diagrams were measured to determine the domain state and microcoercivity spectrum (Roberts et al., 2000; Pike et al., 2001). The diagram shows slightly asymmetrical

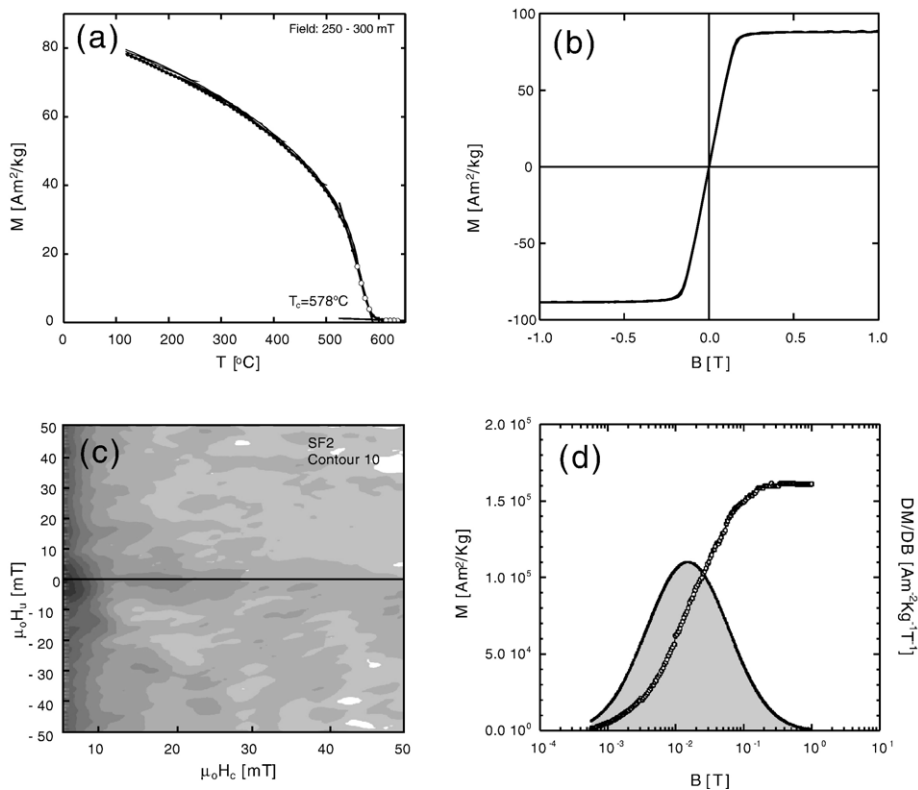


Fig. 3. Rock magnetic experiments on octahedral magnetite single crystals. (a) Determination of the Curie temperature with a modified horizontal translation Curie balance with the applied field cycling between 150 and 300 mT. Open symbols represent the points used for the linear fitting in the determination of the Curie temperature, (b) major hysteresis loop, (c) FORC diagram with a smoothing factor  $SF=2$  in contour intervals of 10 and (d) IRM acquisition curve and coercivity spectrum using software developed by Kruiver et al. (2001). The  $B_{1/2}$  is 15.8 mT and the dispersion parameter of the fitting is  $DP=0.62$ .

vertical contour lines (Fig. 3c), indicative of multidomain particles. The asymmetry can be attributed to minor amount of stress accumulated within the magnetic crystal (Pike et al., 2001) although most of the FORC diagrams are asymmetric due to the intrinsic asymmetry of the measurements as it has been discussed by Muxworthy and Williams (2005).

Isothermal Remanent Magnetization (IRM) acquisition curves up to 2 T were acquired with the alternating gradient magnetometer as well. The curve shape and saturation field are used very often to identify magnetic minerals (e.g., Dunlop and Özdemir, 1997; Evans and Heller, 2003). The coercivity spectra give information on the number of coercivity populations in the sample as well as on their coercivity properties (Kruiver et al., 2001; Heslop et al., 2002; Egli, 2004). Here, the derivative of the IRM acquisition curve has been fitted to a log-Gaussian distribution following the procedure outlined by Kruiver et al. (2001). The analyzed samples show the presence of a very low coercivity phase that saturates at about 200 mT, with a medium acquisition field of 16 mT (Fig. 3d).

#### 4. Cantilever measurements

Five octahedral magnetite single crystals have been measured. The samples have been attached to the cantilever with non-magnetic varnish (GE varnish) supplied by Oxford Instruments. There was at least 1 h between the mounting of the magnetite crystal and the actual measurement to get completely dried varnish ensuring optimal data quality. Samples were measured first in a counterclockwise and then in a clockwise sense of rotation in angular steps of  $10^\circ$ , in various magnetic fields ranging from 50 mT to 2 T. For each field value, the mean torque of the clockwise and counterclockwise measurement is computed in order to eliminate rotational hysteresis effects (Burd et al., 1977; Huq and Lee, 1978). In a saturating magnetic field, the angular dependence of the torque for a magnetite crystal oriented with the magnetization constrained to the (001) plane with the initial field position along the [100] direction, is as follows (Bozorth, 1936; Syono, 1965; Burd et al., 1977):

$$T_{(001)} = -\frac{K_1}{2} \sin(4\theta) \quad (2)$$

where  $K_1$  is the first magnetocrystalline constant for magnetite and  $\theta$  is the orientation of the field with respect to the [100] axis. The value of the first magnetocrystalline anisotropy constant is derived from the coefficient of the Fourier analysis of the signal associated with the  $4\theta$ -term.

Analogously, when the magnetization is constrained to lie in the (110) plane with the initial direction of magnetization in the [001] direction, the magnetic torque in fields higher than saturation is (Bozorth, 1936; Syono, 1965; Burd et al., 1977):

$$T_{(110)} = \frac{K_1}{8} (-2\sin(2\theta) - 3\sin(4\theta)) + \frac{K_2}{64} (-\sin(2\theta) - 4\sin(4\theta) + 3\sin(6\theta)) \quad (3)$$

where  $K_2$  is the second magnetocrystalline anisotropy constant for magnetite. The value of the second magnetocrystalline anisotropy constant is calculated from the  $6\theta$ -term of the Fourier analysis of the signal.

If saturation is reached by the sample, the amplitude of the torque as a function of field must remain constant independent of the strength of the applied field. Theoretically, however, only at infinite fields the saturation magnetization aligns perfectly with the applied field (Burd et al., 1977; Huq and Lee, 1978). In order to calculate the theoretical magnetocrystalline anisotropy constant the “*extrapolation to infinite field*” method has been used (Burd et al., 1977). A package of Matlab subroutines has been developed to compute the anisotropy coefficients.

##### 4.1. Torque measurements

The torques of the five magnetite single crystal samples have been measured as function of angle in the (001) and (110) planes. Measurements in the (001) plane are characterized by a dominant  $4\theta$ -term (Fig. 4a). Overlapping the pure  $4\theta$ -term there is a  $2\theta$ -term due to a slight misorientation of the sample with respect to the (001) plane. Fourier analysis of the signal for the different applied fields (Fig. 4b) indeed shows the dominance of the  $4\theta$ -term (approximately an 85% of the signal) and the presence of the  $2\theta$ -term (14.5% of the signal). The  $6\theta$ -term comprises less than a few percent of the total signal and is considered not significant. The Fourier coefficients show an increase of the intensity with the applied field up to 300 mT, when the sample reaches saturation. With increasing field, in the  $4\theta$ -term first an increase in the signal is observed followed by a further decrease until the signal reaches saturation.

Measurements in the (110) plane are characterized by the combination of several terms (Fig. 4c). The Fourier analysis reveals the presence of a significant  $6\theta$ -term, in agreement with the theoretical expression of the torque in the (110) plane (Eq. (3)).

The magnetocrystalline anisotropy constants for the five crystals are summarized in Table 1 and Fig. 5. The

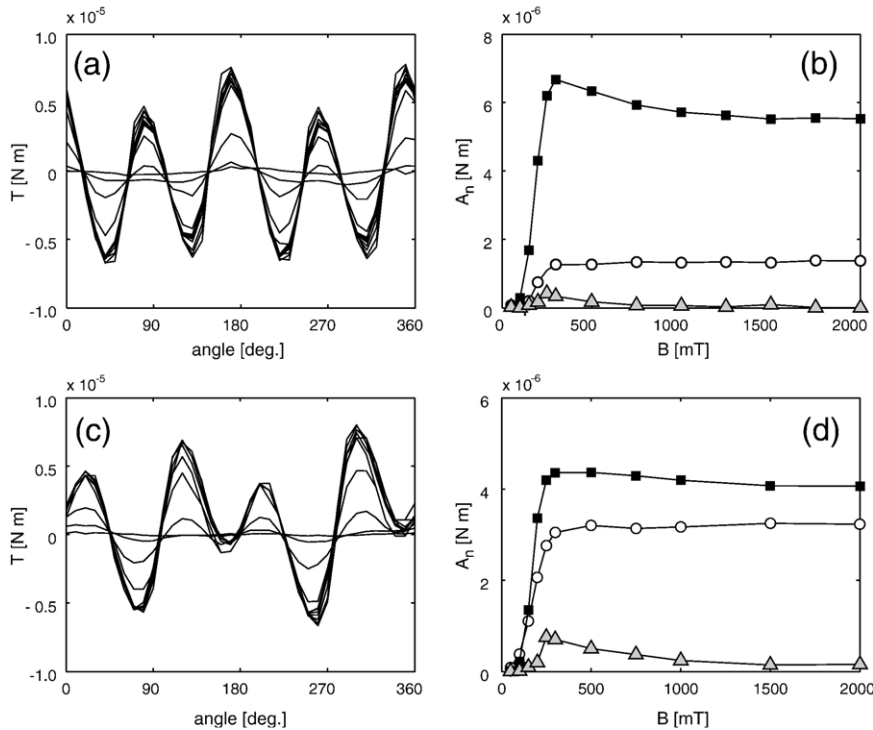


Fig. 4. Measured torque ( $T$ ) for the magnetite single crystal mag.2 (left) and Fourier coefficients ( $A_n$ ) of the torque signal where open circles represent the norm of the  $2\theta$ -term, full squares that of the  $4\theta$ -term and triangles that of the  $6\theta$ -term (right). The upper panels (a, b) show measurements on the (001) and the lower panels (c, d) show measurements on the (110) plane.

first anisotropy constant has been evaluated for the five crystals with the corresponding estimation of the error. A mean value of  $K_1 = (-1.28 \pm 0.13) \times 10^4$  [J m<sup>-3</sup>] was found. For the second anisotropy has also been evaluated in the five crystals. The error could not be determined in one of them, which was measured only at 2 T. A mean value of  $K_2 = (-2.8 \pm 0.1) \times 10^3$  [J m<sup>-3</sup>] was determined. The values of  $K_1$  are more scattered than those of  $K_2$ . This is because the (001) plane of the samples is more difficult to orient than their (110) plane. The mean value of the obtained results is, within the calculated error, similar to the values reported by Syono

(1965) and Sawaoka and Kawai (1967). It should be mentioned that values reported in this work are the only ones providing an estimate of the instrumental and measurement error. Anisotropy constants are utilized in a number of formulas. With the error estimate now available it can be assessed how this would propagate in parameters derived from the anisotropy constants.

#### 4.2. Rotational hysteresis

Rotational hysteresis is the energy stored by a magnetic particle when it rotates in a magnetic field.

Table 1

Magnetocrystalline anisotropy constants computed for the analyzed octahedral magnetite single crystals with their mean value and values reported by Syono (1965)

Sample	Mass [gr.]	$K_1$ [J m <sup>-3</sup> ]	$\Delta K_1$ [J m <sup>-3</sup> ]	$K_2$ [J m <sup>-3</sup> ]	$\Delta K_2$ [J m <sup>-3</sup> ]
mag.2	0.00665	$-1.41 \times 10^4$	$0.013 \times 10^4$	$-2.79 \times 10^3$	$0.555 \times 10^3$
mag.3	0.01645	$-1.17 \times 10^4$	$0.029 \times 10^4$	$-2.77 \times 10^3$	$1.408 \times 10^3$
mag.4	0.00549	$-1.41 \times 10^4$	$0.003 \times 10^4$	$-2.77 \times 10^3$	$1.109 \times 10^3$
mag.5	0.02053	$-1.12 \times 10^4$	$0.013 \times 10^4$	$-2.76 \times 10^3$	~
mag.6	0.01150	$-1.29 \times 10^4$	$0.003 \times 10^4$	$-2.92 \times 10^3$	$0.533 \times 10^3$
Mean value		$-1.28 \times 10^4$	$0.13 \times 10^4$	$-2.8 \times 10^3$	$0.1 \times 10^3$
Syono (1965)		$-1.35 \times 10^4$		$-2.80 \times 10^3$	

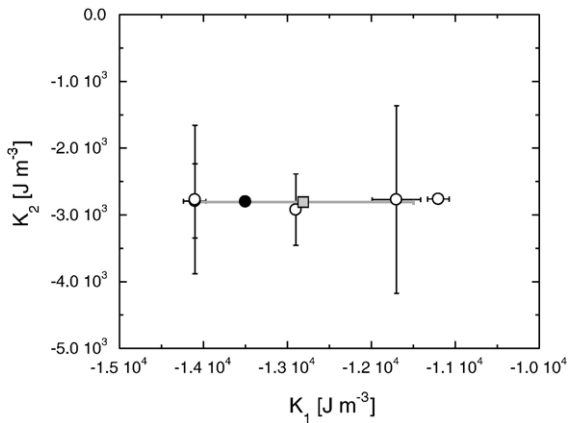


Fig. 5. Calculated values of the two magnetocrystalline anisotropy constants for magnetite (open circles). The error bars are computed from the estimated error based on predictions when representing the Fourier coefficients as a function of applied field. Full circle represents the mean value and the error bars are given by the standard deviation. Full square shows values reported by Syono (1965).

Irreversible magnetization processes only are sensed by rotational hysteresis. The energy increases with increasing applied field until it reaches a maximum related to the anisotropy constant and coercivity of the particles. Above this point it decreases to zero at a rate that depends on the magnetic particles, their domain state, oxidation, or orientation. It is not a very often used parameter; however it can provide useful information about the nature of the magnetic particles and the number of populations, their oxidation state, or the degree of exchange interaction between particles. In particular, core–rim interaction is one of the most difficult parameters to evaluate in rock magnetism but plays very important role in the remanence of sediments when magnetite particles are surrounded by an oxidized or partially maghemitized rim.

If the torque of an anisotropic specimen in a magnetic field is  $T(\theta)$ , the rotational hysteresis is computed as the integral over the full rotation (e.g., Bozorth, 1951; Collinson and Creer, 1960; Stacey and Banerjee, 1974).

$$W_R = \frac{1}{2\pi} \int_0^{2\pi} T(\theta) d\theta \quad (4)$$

$W_R$  is the rotational hysteresis in Joules,  $\theta$  is the angle between the applied field and the origin of coordinates in radians, and  $T$  is the magnetic torque in N m.

Several theoretical models have been proposed to explain the variations of rotational hysteresis with applied field (Stoner and Wohlfarth, 1948; Owens, 1981). The general experimental feature that  $W_R$  displays is a peak related with the anisotropy constants (Owens, 1981). The position of the maximum value of  $W_R$  and its value has been used to identify magnetic phases in natural samples (Schmidbauer, 1988; Keller and Schmidbauer, 1996, 1999; Schmidbauer and Keller, 1996; Muxworthy et al., 2002). It has also been used to study the degree of oxidation of magnetic particles (Day et al., 1970).

The rotational hysteresis energy is computed as half of the area enclosed by the torque curve when the specimen is rotated twice, first in one sense of rotation and then in the opposite sense (Fig. 6a). The rotational hysteresis has been evaluated as a function of applied field for all the analyzed samples. It shows a maximum value, centered on approximately 150 mT. The peak of rotation hysteresis coincides with the expected values (Fig. 6b). The values are comparable with results reported previously for multidomain magnetite (Muxworthy, 2002). In fields above this maximum value,  $W_R$  values decay and tend to zero. The curve is narrower than earlier reported because the samples analyzed in this work are single crystals and samples previously analyzed consisted on non-oriented assemblages of

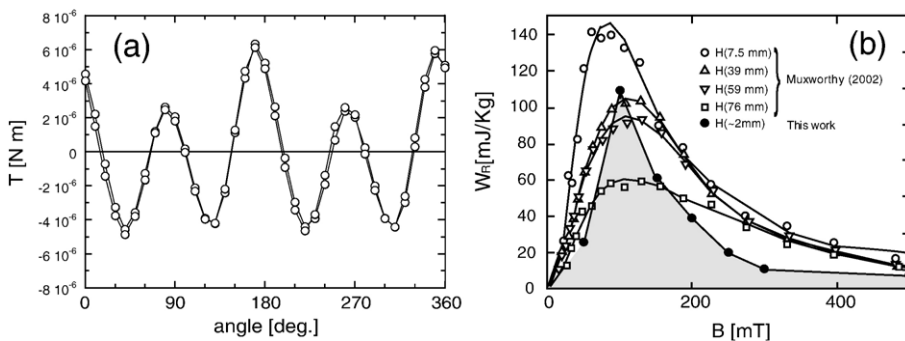


Fig. 6. Rotational hysteresis on a magnetite single crystal. (a) Rotational hysteresis is seen as the area (gray area) between the torque measured in the clockwise direction and the torque measured in the counterclockwise sense with an applied field of 150 mT. (b) Rotational hysteresis loss as a function of applied field (full symbols) compared with reported data (open symbols) (Muxworthy et al., 2002).

multidomain crystals (Elk, 1993). The rotational hysteresis can also be underestimated due to the measurement procedure. When the curves are measured the clockwise and counterclockwise curves coincide at  $0^\circ$  and  $360^\circ$ . To avoid this problem the curves are usually calculated through  $540^\circ$  between  $-90^\circ$  and  $450^\circ$  and only used the data from  $0^\circ$  to  $360^\circ$ . The device used here does not allow rotations of more than  $360^\circ$ . To avoid this problem the rotational hysteresis has been computed as twice the value between  $90^\circ$  and  $270^\circ$ .

## 5. Discussion

### 5.1. Magnetocrystalline anisotropy determinations

Strictly speaking, the constant determined by torque magnetometry is a combination of magnetocrystalline and magnetostriction constants (Ye et al., 1994). The magnetocrystalline anisotropy constant alone can be determined by ferromagnetic resonance, which has been evaluated for magnetite by Bickford (1949, 1950). For magnetite the magnetostriction term is small and it has been neglected by most studies (Syono, 1965; Kakol et al., 1991).

### 5.2. Instrument properties and performance

The measurement of a sample in the two senses of rotation takes about 20 min per applied field step. This may seem rather long, but nevertheless, the cantilever instrument is four times faster than other torque magnetometers available for rock magnetic fabrics (Bergmüller et al., 1994; Martín-Hernández and Hirt, 2001). So, the device allows a more precise evaluation of the desired parameters within the same time.

Samples with a combination of low-coercivity and high-coercivity minerals would need longer measuring time when the two subfabrics are separated. The presence of the latter makes it difficult to separate magnetic subfabrics due to the absence of saturation in the available magnetic fields (Martín-Hernández and Hirt, 2004). However this problem is not exclusive of this device but common to all torque magnetometers.

As with many instruments, cantilevers have a certain dynamic range. Samples with a very weak magnetization (e.g., weakly anisotropic paramagnetic samples or diamagnetic samples) are affected by the background signal. Samples with a very strong magnetization are out of the linear range between magnetization and capacitance and therefore not properly calibrated. A more robust feedback coil would be necessary in order to calibrate the instrument at higher magnetization ranges. The minimum

detectable difference of magnetization estimated with the magnetization of the feedback coil is  $\Delta m \sim 10^{-7} \text{ A m}^2$ . The detectable range of differences in susceptibility estimated for a sample of  $27 \text{ mm}^3$  is  $\Delta K \sim 10^{-5} \text{ [S.I.]}$ .

### 5.3. Measurements

The measurements carried out are consistent with the theoretical expressions for the selected measuring planes (Fig. 4). An overlapping  $2\theta$ -term shows up in the measurements on the (001) plane which is supposed to be due to a small misorientation of the measuring plane (Fig. 4a). The  $2\theta$ -term has been attributed only to the magnetocrystalline anisotropy. In magnetite shape anisotropy is also important but for magnetite particles larger than  $20 \mu\text{m}$ , shape anisotropy becomes less important (Dunlop and Özdemir, 1997). Due to the big size of the studied samples, this term has been neglected. The presence of this term might also be related with accumulation of strain due to the extraction process from the rock. Syono (1965) also reported a  $2\theta$ -term in this measuring plane. Annealing might liberate the strain from the samples. Further work should be done to corroborate this hypothesis.

The two Fourier coefficients for the  $4\theta$ -term and  $6\theta$ -term display a similar behaviour, they increase until a maximum at the saturation field and followed by a decrease until a constant value is reached. Similar behaviour has been reported already in natural samples for the  $4\theta$ -term by Bergmüller and Heller (1996). It can be related with the asymptotic approximation of the magnetization to saturation.

## 6. Conclusion and perspective

Cantilever torque magnetometry has been revealed as an excellent tool also for rock magnetic analysis. The instrument allows measurement as a function of applied fields ranging from 0 to 2 T in the two senses of rotation. The minimum detectable difference of magnetization estimated with the magnetization of the feedback coil is  $\Delta m \sim 10^{-7} \text{ A m}^2$ . The detectable range of differences in susceptibility estimated for a sample of  $27 \text{ mm}^3$  is  $\Delta K \sim 10^{-5} \text{ [S.I.]}$ . Cantilever magnetometers can be used for all utilities already set out for torque magnetometry applied to natural samples, e.g. separation of magnetic subfabrics (Hrouda and Jelinek, 1990; Martín-Hernández and Hirt, 2004). The instrument operates distinctly faster than classic torque magnetometers. It can be optimized for a specific dynamic range if desired. Because the two senses of rotation can be measured, it is also



possible to measure rotational hysteresis loss as a function of applied field. This would allow evaluation of magnetic interaction between the cores and oxidation rims of magnetic particles in rocks or the degree of interaction between particles of the same population (Muxworthy, 2001). Rotational hysteresis loss has been shown to be useful in rock magnetic studies, in particular to study the degree of oxidation in basalts (Day et al., 1970; Manson and O'Reilly, 1976; Schmidbauer and Keller, 1994), coercivity changes on heating (Cowan and O'Reilly, 1972) and coercivity of polluting particles (Muxworthy et al., 2002).

The anisotropy measurements carried out in the present study are consistent with the theoretical expressions for the selected measuring planes (Fig. 4). An overlapping  $2\theta$ -term shows up in the measurements on the (001) plane which is argued to be due to a small deviation of the measuring plane (Fig. 4a). The results obtained corroborate the values for  $K_1 = -1.35 \times 10^4$  [ $\text{J m}^{-3}$ ] and  $K_2 = -2.80 \times 10^3$  [ $\text{J m}^{-3}$ ] of magnetite that have been used in multiple applications such as micro-magnetic calculations (Enkin and Dunlop, 1987; Carvallo et al., 2003; Muxworthy et al., 2004), analysis of coercivity properties (Ozdemir, 2000) or hysteresis simulations (Tauxe et al., 2002).

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